

Rotational Absolute Magnetic Encoder Version 30 mm HP Position Sensor



LINKS TO ADDITIONAL RESOURCES



QUICK REFERENCE DATA				
Sensor type ROTATIONAL, magnetic technol				
Output type	Cable			
Market appliance	Industrial			
Dimensions	Diameter 30 mm			

FEATURES



- · Hall effect principle
- · High precision (HP), high resolution
- Especially dedicated to harsh conditions (vibrations, shocks, CEM, ...)
- Not sensitive to external magnetic fields and temperature
- Not sensitive to moisture and pollution
- Plug and play
- Protected design, patent EP 2711663
- Material categorization: for definitions of compliance please see www.vishay.com/doc?99912

ELECTRICAL SPECIFICATIONS		
PARAMETER		
Voltage supply	5 V ± 0.25 V	
Current supply	≤ 130 mA at 5 V	
Output	SSI	
Connection	Shielded cable	
Useful electrical angle	360°	
Absolute accuracy at 25 °C	± 0.03° > 13 bits	
Absolute accuracy at -40 °C to +105 °C	± 0.05° ~ 13 bits	
Resolution	≈ 0.0028° (17 bits, 131 072 points) over 360°	
Startup time	≤ 20 ms	
Refresh time	≤ 110 µs	
Latency time	100 μs ≤ latency time ≤ 200 μs	
Sampling rate	10 kHz ± 5 %	

MECHANICAL SPECIFICATIONS			
PARAMETER			
Mechanical angle 360°			
Maximum speed rotation	50 rpm (up to 1000 rpm with decreasing of accuracy, see "Maximum Speed vs. Accuracy" chart)		
Weight	51 g ± 5 g		



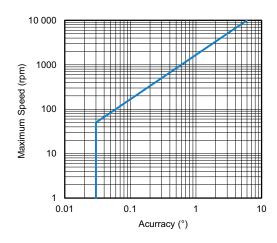
Vishay MCB

SAP PART NUMBERING GUIDELINES									
TYPE	MODEL	DESIGN	SIZE (mm)	TYPE	FUNCTION	ACCURACY (BITS)	RESOLUTION (BITS)	OUTPUT	PACKAGING
R = rotational	AM	E = encoder with housing	030	М	1	13	17	J = SSI CCW	B = box

PERFORMANCE				
PARAMETER				
Operating temperature range	-40 °C to +105 °C			
Storage temperature range	-45 °C to +105 °C			
Acceleration (2)	100 g for 1 s			
Vibration (three major axis) (2)	Vibration profile 1: $0.05 g^2$ /Hz, $20 Hz$ to $2000 Hz$ for 1 h along Vibration profile 2: see figure 1 - tested according "Endurance" profile Vibration profile 3: see figure 2 - tested according "Endurance" profile Vibration profile 4: see figure 3 - tested according "Endurance" profile Vibration profile 5: see figure 4 - tested according "Endurance" profile			
Shock (2)	180 g, 14 ms, 1/2 sine			
EMC ⁽²⁾	 According to MIL-STD-461F: RE101: radiated emissions, magnetic field, 30 Hz to 100 kHz - limit for all navy applications to figure RE101-2 RE102: radiated emissions, electric field, (10 kHz to 18 GHz) - curve for fixed wing external and helicopters at 2 MHz to 18 GHz, according to figure RE102-3 (1) RS101: radiated susceptibility, magnetic field, 30 Hz to 100 kHz - limit for all navy applications according to figure RS101-1 RS103: radiated susceptibility, electric field, (2 MHz to 40 GHz) - 200 V/m, according to Table XI, aircraft external 			
Humidity ⁽²⁾	HR ≤ 88 % (non-condensing) operating 48 hours			

Notes

MAXIMUM SPEED VS. ACCURACY CHART (latency time excluded)



⁽¹⁾ For the test setup, the metallic support of the electronic support is directly bonded with a braid to the ground plane and additional connection of the cable shielding to the ground plane

⁽²⁾ Tests have been performed on electronic board and magnet without the mechanical housing of the encoder



VIBRATION PROFILES

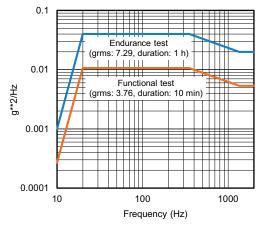


Fig. 1 - Vibration Profile 2

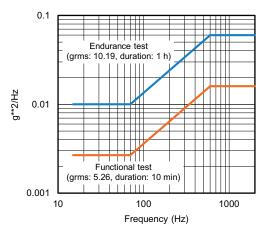


Fig. 2 - Vibration Profile 3

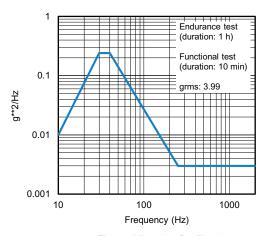


Fig. 3 - Vibration Profile 4

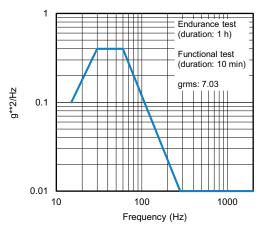
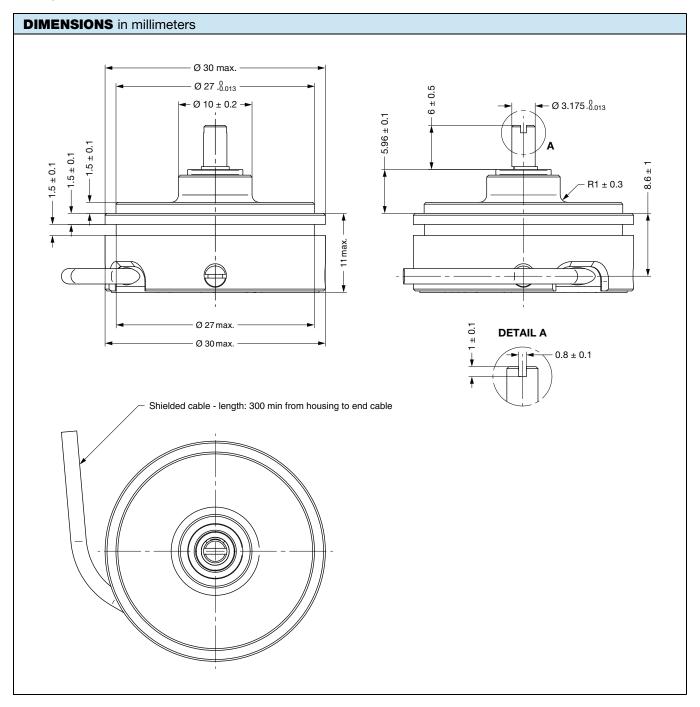


Fig. 4 - Vibration Profile 5



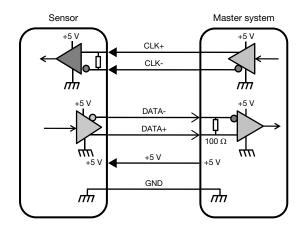




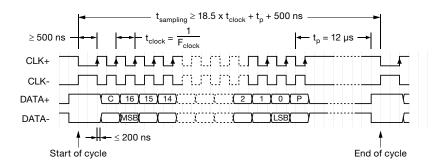
ELECTRICAL INTERFACE DESCRIPTION - SSI INTERFACE

6 WIRES CONNECTION				
NAME	WIRE COLOR	WIRE SIZE		
GND	Black	32 AWG		
+5 V	Red	32 AWG		
CLK+	White	32 AWG		
CLK-	Blue	32 AWG		
DATA+	Yellow	32 AWG		
DATA-	Green	32 AWG		

SSI PARAMETERS				
Output code	Binary			
Data differential interface	RS422 according to EIA-RS422			
CLK differential interface	RS422 according to EIA-RS422			
Minimum clock frequency	300 kHz			
Maximum clock frequency	4 MHz			
Data bit (n)	19 bits			
C: consistency of all internal magnetic cells outputs	Bit "C": $0 \rightarrow \text{compliant} / 1 \rightarrow \text{not compliant}$			
16-0: angle	Bit "16-0": angle value			
P: parity of this bits "C" to "16"	Bit "P": $0 \rightarrow \text{pair sum } / 1 \rightarrow \text{impair sum}$			



Timing Diagram

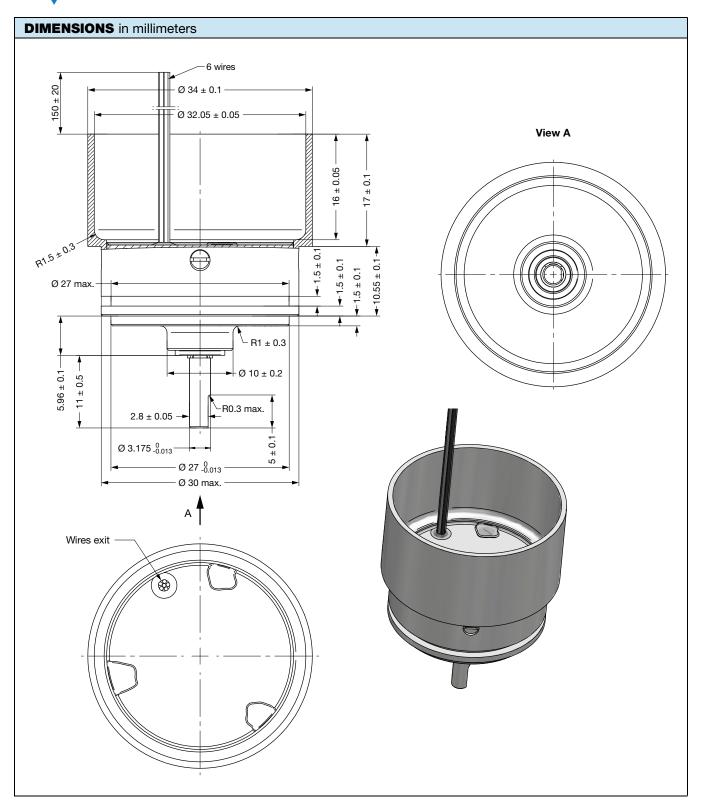


OPTIONS

- Other design on request (mechanical interfaces, electrical interfaces, ...)
- On request: axial output wires (see upcoming Dimensions table for details)



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